

IN THE SPECIFICATION:

Please replace paragraph 0009 with the following amended paragraph:

Moreover, an advantage is if the surrounding track has a closed form around the application facility for determining the adhesive line[. For], the adhesive line on the surrounding track on the substrate is monitored by means of a projection.

Please replace paragraph 0017 with the following amended paragraph:

According to a preferred embodiment where three cameras are used, a first camera covers a range of angles from $[[100^\circ]] -10^\circ$ to 130° , a second camera a range of angles from 110° to 250° , and a third camera a range of angles from 230° to 10° .

Please replace paragraph 0019 with the following amended paragraph:

Moreover, an advantage is if the edge of the adhesive line is determined on a circular line around the application facility, the adhesive line is detected, at any progression, in a defined area. According to a preferred embodiment, the center of the circular line or of the surrounding track essentially coincides with the site from which the adhesive emanates to form the adhesive line, whereby each camera monitors at least one segment of the circle formed by the circular line.

Please replace paragraph 0045 with the following amended paragraph:

Figure 4 shows another progression of an adhesive line 20. The field of view that is active is shown, namely which camera has the corresponding field of view is shown as a rectangle while traveling along the adhesive line. Only one camera is active at one site, and two cameras are active at another site. Which field of view is active, depends on the progression of the adhesive line relative to the circular caliper that is used to monitor the adhesive line on the

substrate.

Please replace paragraph 0063 with the following amended paragraph:

Figure 9 shows in the second, lower position of both edges of the adhesive line ck are at the end of the track-shaped progression in image strip 33 that is indicated by the straight lines 330. Consequently, only the camera assigned to image strip 330 is still active. Considering the overall progression, a global coordinate system results for the monitoring of the adhesive line 20 due to the circular caliper 90 being arranged around the application facility [11]] 11. The global coordinate system is arranged to be constant with regard to the application facility 11. Consequently, the software for assessment of the adhesive line 20 must take into consideration only the progression on the circular caliper 90.